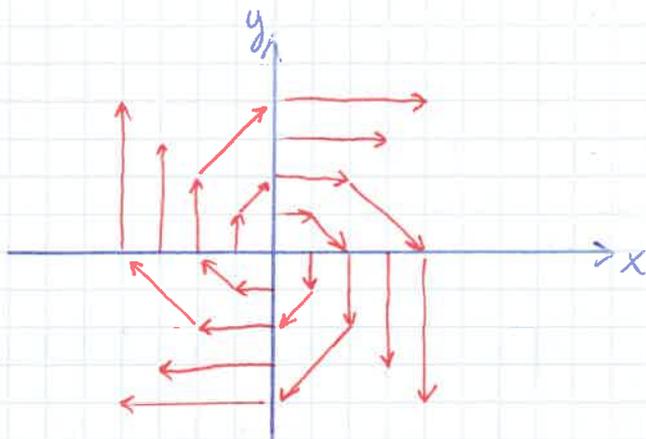


AI1)

$$\delta f = y dx - x dy$$

$$1) \vec{F} = \begin{pmatrix} y \\ -x \end{pmatrix}$$



$$2) \text{rot } \vec{F} = 0?$$

$$\begin{pmatrix} \partial/\partial x \\ \partial/\partial y \end{pmatrix} \times \begin{pmatrix} y \\ -x \end{pmatrix} = \begin{matrix} \text{rot} \\ \text{rot} \end{matrix} -1 - 1 = \underline{-2} \neq 0$$

\Rightarrow inexactes Differential

wegabhängiges Vektorfeld

$$3) \begin{pmatrix} x(t) \\ y(t) \end{pmatrix} = \begin{pmatrix} -\cos(t) \\ \sin(t) \end{pmatrix} \quad 0 \leq t \leq \pi$$

$$\begin{pmatrix} \dot{x} \\ \dot{y} \end{pmatrix} = \begin{pmatrix} \sin(t) \\ \cos(t) \end{pmatrix} \Rightarrow \begin{matrix} dx = \sin(t) dt \\ dy = \cos(t) dt \end{matrix}$$

$$\int y dx - x dy =$$

$$\int [\sin(t) \cdot \sin(t) - (-\cos(t)) \cos(t)] dt$$

$$\int (\sin^2(t) + \cos^2(t)) dt = \int_0^\pi 1 dt = \underline{\pi}$$

$$4) \begin{pmatrix} x(t) \\ y(t) \end{pmatrix} = \begin{pmatrix} 1 \\ 0 \end{pmatrix} \quad -1 \leq t \leq 1$$

$$\dot{x} = 1 \Rightarrow dx = dt; \quad dy = 0$$

$$\int 0 \cdot dx - 1 \cdot dy \stackrel{0}{=} 0 = \underline{0}$$

Warum 0? Kraftvektoren stehen immer normal auf Wegrichtung!

AI 2)

$$F = \begin{pmatrix} xy \\ 10 \\ yz \end{pmatrix} \quad \begin{pmatrix} x(t) \\ y(t) \\ z(t) \end{pmatrix} = \begin{pmatrix} \cos(t) \\ \sin(t) \\ 1 \end{pmatrix} \quad 0 \leq t \leq 2\pi$$

$$\delta f = \delta W = xy dx + dy + yz dz$$

$$\begin{pmatrix} x \\ y \\ z \end{pmatrix} = \begin{pmatrix} -\sin(t) \\ \cos(t) \\ 1 \end{pmatrix} \Rightarrow \begin{aligned} dx &= -\sin(t) dt \\ dy &= \cos(t) dt \\ dz &= dt \end{aligned}$$

$$\int \delta W = \int \cos(t) \sin(t) (-\sin(t)) dt + \cos(t) dt + \sin(t) \cdot 1 dt$$

$$= \int \cos(t) \cdot [1 - \sin^2(t)] dt + 1 \cdot \sin(t) dt =$$

$$= \int [\cos^3(t) + 1 \cdot \sin(t)] dt =$$

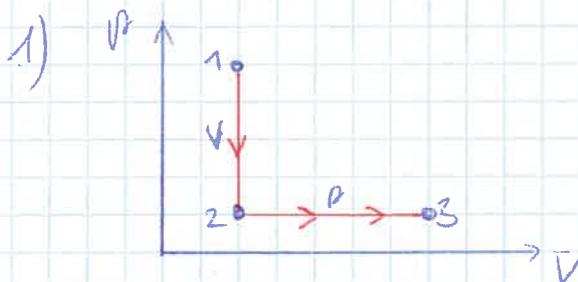
→ WOLFRAMALPHA

$$\int \cos^3(t) dt = \frac{1}{12} (9 \sin(t) + \sin(3t)) \Big|_0^{2\pi} = 0$$

$$= \int 1 \cdot \sin(t) dt = -1 \cdot \cos(t) - \int \cos(t) dt$$

$$= -1 \cdot \cos(t) - \sin(t) \Big|_0^{2\pi} = \underline{\underline{-2\pi}}$$

AI 3)



$$W_{12} = -\int p dV = 0$$

$$Q_{12} = \int T ds$$

$$S = \frac{3}{2} R \ln(pV^{5/3})$$

$$dS = \frac{3}{2} R \cdot \left[\frac{V^{5/3}}{pV^{5/3}} dp + \frac{p \cdot \frac{5}{3} V^{2/3}}{pV^{5/3}} dV \right]$$

$$= \frac{3}{2} R \left[\frac{dp}{p} + \frac{5dV}{3V} \right]$$

$$Q_{12} = \int_{32}^1 \frac{pV}{R} \frac{3}{2} R \frac{dp}{p} = \frac{3}{2} V p \Big|_{32}^1$$

$$= \frac{3}{2} \cdot 1 \cdot [1 - 32] = \underline{\underline{-\frac{3}{2} \cdot 31}}$$

$$Q_{12} + W_{12} = \underline{\underline{-\frac{3}{2} \cdot 31}} = U_2 - U_1 = \frac{3}{2} p_2 V_2 - \frac{3}{2} p_1 V_1$$

$$= \frac{3}{2} \cdot 1 \cdot 1 - \frac{3}{2} \cdot 32 \cdot 1 = \underline{\underline{-\frac{3}{2} \cdot 31}} \checkmark$$

$$Q_{23} = ? \quad W_{23} = ?$$

$$W_{23} = -\int p dV = -p(V_3 - V_2) = -1 \cdot (8 - 1) = \underline{-7}$$

$$Q_{23} = \int T dS$$

$$= \int \frac{pV}{R} \cdot \frac{3}{2} \cdot \frac{5}{3} R \frac{dV}{V} =$$

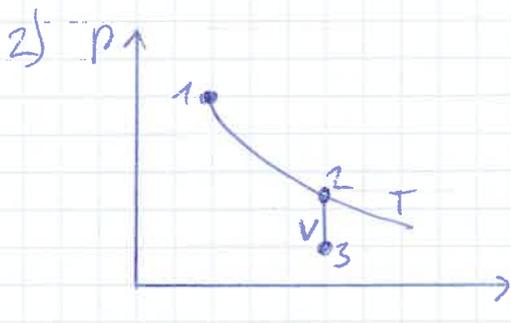
$$= \int \frac{5}{2} p dV = \frac{5}{2} p (V_3 - V_2) = \frac{5}{2} \cdot (8 - 1) = \underline{\frac{5}{2} \cdot 7}$$

$$U_3 - U_2 = Q_{23} + W_{23}$$

$$\Rightarrow -7 + 7 \cdot \frac{5}{2} = \frac{3}{2} p_3 V_3 - \frac{3}{2} p_2 V_2 =$$

$$\frac{3}{2} \cdot 1 \cdot 8 - \frac{3}{2} \cdot 1 \cdot 1$$

$$\underline{-\frac{14}{2} + \frac{35}{2} = \frac{21}{2}} \quad \checkmark$$



$$W_{12} = -\int p dV$$

$$pV = \text{const.} = 32 \cdot 1 = \underline{32}$$

$$p = \frac{32}{V}$$

$$W_{12} = -\int \frac{32}{V} dV =$$

$$-32 \ln\left(\frac{V_2}{V_1}\right) = \underline{-32 \ln(8)}$$

$$Q_{12} = \int T dS = \int \frac{pV}{R} \frac{3}{2} R \left[\frac{dp}{p} + \frac{5}{3} \frac{dV}{V} \right]$$

$$= \int 32 \cdot \frac{3}{2} \cdot \left[-\frac{32}{V^2 32} dV + \frac{5}{3} \frac{dV}{V} \right]$$

$$= \int 32 \cdot \frac{3}{2} \left[\frac{2}{3} \frac{dV}{V} \right]$$

$$= 32 \ln\left[\frac{V_2}{V_1}\right] \Big|_1^8 = \underline{32 \ln(8)}$$

$$\frac{dp}{dV} = -\frac{32}{V^2}$$

$$dp = -\frac{32}{V^2} dV$$

$$pV = 32$$

$$p_2 = p_1 \left(\frac{V_1}{V_2}\right) =$$

$$32 \cdot \left(\frac{1}{8}\right) = \underline{4}$$

$$\underline{U_2 - U_1 = 0 = Q_{12} + W_{12}} \quad \checkmark$$

$$W_{23} = -\int p dV = 0$$

$$Q_{23} = \int T dS = \int \frac{pV}{R} \frac{3}{2} R \frac{dp}{p} = \int \frac{3}{2} V dp = \frac{3}{2} V \ln \frac{1}{4}$$

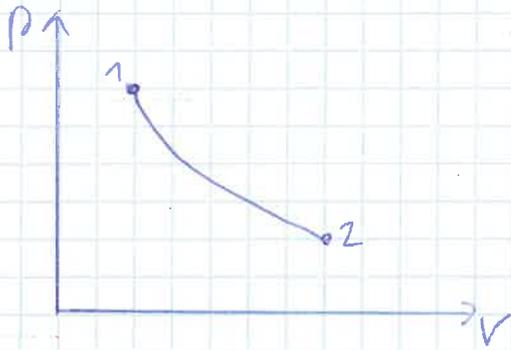
$$U_3 - U_2 = \frac{3}{2} p_3 V_3 - \frac{3}{2} p_2 V_2 =$$

$$= \frac{3}{2} \cdot 8 \cdot (1 - 3)$$

$$\frac{3}{2} \cdot [1 \cdot 8 - 4 \cdot 8] = \underline{-36}$$

$$= \underline{-36}$$

3)



$$Q_{12} = 0 \text{ (adiabatisch)}$$

$$dS = 0 \Rightarrow pV^{5/3} = \text{const.}$$

$$W = -\int p dV = -\int \frac{C_1}{V^{5/3}} dV = -\frac{3}{2} \frac{C_1}{V^{2/3}} \Big|_1^8$$

$$= -\frac{3}{2} \cdot 32 \cdot \left[\frac{1}{8^{2/3}} - \frac{1}{1} \right]$$

$$= -\frac{3}{2} \cdot 32 \cdot -\frac{3}{4}$$

$$= \underline{\underline{36}}$$

$$U_2 - U_1 = \frac{3}{2} p_2 V_2 - \frac{3}{2} p_1 V_1 =$$

$$\frac{3}{2} [8 \cdot 1 - 1 \cdot 32] = \underline{\underline{36}}$$